

Real quadratic form \Rightarrow

An expression of the form $\sum_{j=1}^n \sum_{i=1}^n a_{ij} x_i x_j$, where a_{ij} are real and $a_{ij} = a_{ji}$, is said to be a real quadratic form in n variables x_1, x_2, \dots, x_n .

The matrix notation for the quadratic form is $X^T A X$ where $X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$

and $A = (a_{ij})_{n \times n}$

A is real symmetric matrix since $a_{ij} \in \mathbb{R}$ and $a_{ij} = a_{ji}$.

To every real quadratic form in n variables is associated an $n \times n$ real symmetric matrix which is said to be the matrix of the quadratic form.

Examples \Rightarrow

$\Rightarrow 5x_1^2 + 2x_1x_2 - x_2^2$ is a real quadratic form in two variables x_1, x_2 .

The associated matrix is $\begin{bmatrix} 5 & 1 \\ 1 & -1 \end{bmatrix}$

2) $x_1 x_2 - x_2 x_3$ is a real quadratic form in three variables x_1, x_2, x_3

The associated matrix is
$$\begin{bmatrix} 0 & \frac{1}{2} & 0 \\ \frac{1}{2} & 0 & -\frac{1}{2} \\ 0 & -\frac{1}{2} & 0 \end{bmatrix}$$

3) $x_1^2 - x_2^2 + 2x_3^2$ is a real quadratic form in three variables.

The associated matrix is the diagonal

matrix
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

Definitions \Rightarrow

A real quadratic form

$Q(x_1, x_2, \dots, x_n)$ assumes the value 0 when $x = 0$. But Q takes different real values for different non-zero x .

A real quadratic form $Q = x^t A x$ is said to be

i) positive definite if $Q > 0, \forall x \neq 0$

ii) positive semidefinite

if $Q \geq 0 \forall x$ and $Q = 0$ for some x

iii) Negative definite if $Q < 0 \forall X \neq 0$.

iv) Negative semi definite if $Q \leq 0, \forall X$ and $Q = 0$ for some $X \neq 0$.

v) Indefinite if $Q \geq 0$ for some $X \neq 0$ and $Q \leq 0$ for some other $X \neq 0$.

Examples \Rightarrow

1) Let $Q = Q(x_1, x_2, x_3) = x_1^2 + 2x_2^2 + 4x_3^2 + 2x_1x_2 - 4x_2x_3 - 2x_3x_1$.

$$Q = (x_1 + x_2 - x_3)^2 + (x_2 - x_3)^2 + 2x_3^2$$

≥ 0 for all $X = (x_1, x_2, x_3)$

and $Q = 0$ only when $x_1 = x_2 = x_3 = 0$.

Therefore Q is positive definite.

The associated matrix is

$$\begin{bmatrix} 1 & 1 & -1 \\ 1 & 2 & -2 \\ -1 & -2 & 4 \end{bmatrix}$$

is therefore positive definite.

2) Let $Q(x_1, x_2, x_3) = x_1^2 + 2x_2^2 + 2x_3^2 + 2x_1x_2 - 4x_2x_3 - 2x_3x_1$

$$\Rightarrow Q = (x_1 + x_2 - x_3)^2 + (x_2 - x_3)^2$$

$\Rightarrow Q \geq 0$ for all $X = (x_1, x_2, x_3)$.

But Q may be zero for non-zero (x_1, x_2, x_3) . For example, $Q(0, 1, 1) = 0$.

Therefore Q is positive semi-definite.

$$3) \text{ Let } Q(x_1, x_2, x_3) = x_1^2 + x_2^2 + 2x_1x_2 + 2x_2x_3 + 2x_3x_1$$

$$\Rightarrow Q = (x_1 + x_2 + x_3)^2 - x_3^2$$

Q is indefinite because $Q > 0$ for some $x = (x_1, x_2, x_3)$ and $Q < 0$ for some x .

For example ~~$Q(1, 1, 0) > 0$~~

$$Q(1, 1, 0) > 0$$

$$Q(0, -1, 1) < 0$$

By the transformation $x = PY$ where $|P| \neq 0$ the real quadratic form $Q = x^t A x$ transforms to $Y^t (P^t A P) Y$. This is a quadratic form in Y . [Here A is symmetric]

Since $P^t A P$ is a symmetric matrix then Q is transformed to a quadratic form Q' . And Q' is said to be congruent to Q .

For a real symmetric matrix A of rank r ($\leq n$), \exists a non-singular matrix P such that $P^t A P$ becomes a diagonal matrix

$$D = \begin{bmatrix} I_m \\ -I_{h-m} \\ 0 \end{bmatrix}$$

[signature = $2m - h$]

of rank h

where $0 \leq m \leq r$

Therefore by a suitable transformation

$X = PY$, where P is non-singular.

The real quadratic form Q transforms

$$\text{to } y_1^2 + y_2^2 + \dots + y_m^2 - y_{m+1}^2 - y_{m+2}^2 - \dots - y_r^2$$

where $0 \leq m \leq r \leq n$.

This is said to be the normal (diagonal) form of Q .

Theorem \Rightarrow The integer m which is the number of positive elements in the normal (diagonal) form of a real quadratic form Q , is invariant.

Definitions The rank of a real quadratic form is defined to be the rank of associated real symmetric matrix.

The signature of a real quadratic form is defined to be the signature of the associated real symmetric matrix.

$$Q(x_1, x_2, x_3) = x_1^2 + 2x_2^2 + 2x_3^2 + 2x_1x_2 - 4x_2x_3 - 2x_3x_1$$

$$\Rightarrow Q = (x_1 + x_2 - x_3)^2 + (x_2 - x_3)^2$$

$$\Rightarrow Q \geq 0 \text{ for all } X = (x_1, x_2, x_3)$$